



DATA SHEET

The DS-90 is a member of the DS series of Electric Encoders<sup>™</sup>, based on Netzer Precision proprietary technology. The Electric Encoder<sup>™</sup> offers many advantages - some unparalleled

- Low profile (10 mm)
- Hollow, floating shaft
- No bearings or other contacting elements
- High resolution and precision
- High tolerance to temperature extremes, shock, moisture, EMI, RFI and Magnetic fields
- Very low weight
- Holistic signal generation
- Analog or Digital interfaces

#### General

Angular resolution	19-21 bit	
Maximum tested static error	±0.010°	
Extended accuracy static error	±0.006°	
Maximum operational speed	2000 rpm	
Measurement range	Unlimited rotation	
Rotation direction	Adjustable CW/CCW*	
Power On - Max. operational speed	3.3 RPM <=20°/sec	
Build In test BIT	Optional	

\* Default same direction from bottom side of the encoder

#### Mechanical

Allowable mounting eccentricity	±0.1 mm	
Allowable axial mounting tolerance	±0.1 mm	
Rotor inertia	4,242 gr · mm²	
Total weight	55 gr	
Outer Ø /Inner Ø/ Height	90 / 50 / 10 mm	
Material (stator, rotor)	Ultem™ polymer / TRVX-50	

The Electric Encoder<sup>™</sup> is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor, This feature makes the Electric Encoder<sup>™</sup> forgiving to mounting tolerances, mechanical wander etc.

The absence of components such as ball bearings, flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder<sup>™</sup> virtually failure free.

The internally shielded, DC operated Electric Encoder<sup>™</sup> includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

The output signals of Electric Encoder<sup>TM</sup> are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.

#### Electrical

Supply voltage	5V ± 5%
Interconnection	Shielded cable
Cable length	1,500 mm MAX

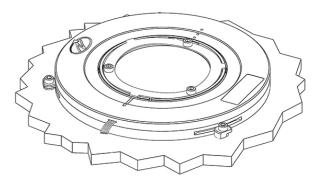
#### Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4	
Operating temperature range	-40°C to +85°C	
Storage temperature	-50°C to +100°C	
Relative humidity	98% Non condensing	
Shock endurance	100 g for 11 ms	
Vibration endurance	20 g 10 – 2000 Hz	
Protection	IP 40	



DS-90 Qcore





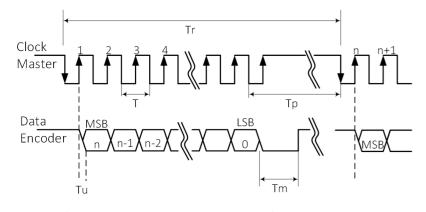




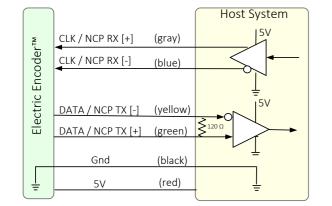


# **Digital SSi Interface**

Synchronous Serial Interface (SSI) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations	
n	Total number of data bits	12 - 22	
Т	Clock period		
f= 1/T	/T Clock frequency 0.5 - 2.0 MHz		
Tu	Bit update time 200 nsec		
Тр	Pause time 26 - ∞ µsec		
Tm	Monoflop time	>25 µsec	
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec	
fr=1/Tr	Data request frequency		



### SSi / BiSS Output signal parameters

Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock frequency	0.5 ÷ 2.0 MHz
Position update rate (Max)	30 kHz
Current consumption	90 mA

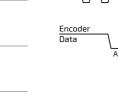
## SSi / BiSS interface wires color code

Clock +	Grey	Clock	
Clock -	Blue		
Data -	Yellow	Data	
Data +	Green		
GND	Black	Ground	
+5V	Red	Power supply	

# Software tools: (SSi / BiSS - C)

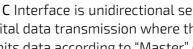
Advanced calibration and monitoring options are available by using the factory supplied Electric Encoder Explorer software, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.





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# **Digital BiSS-C Interface**

BiSS – C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode). The BiSS-C interface as the SSi is based on RS-422 standards.

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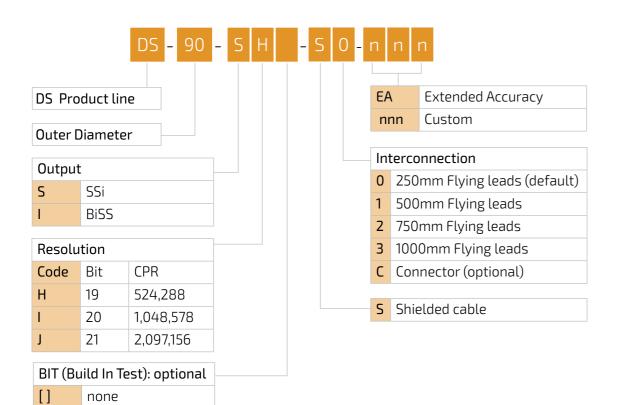
bit #		Description	Default	Length
29	Ack	Period during which the encoder calculates the absolute position , one clock cycle	0	1/clock
28	Start	Encoder signal for "start" data transmit	1	1 bit
27	"0"	"start" bit follower	0	1 bit
826	AP	Absolute Position encoder data		
7	Error	Error (amplitude levels)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x6 + x1 + x0$ . It is transmitted MSB first and inverted.		6 bits
		The start bit and "0" bit are omitted from the		
		CRC calculation.		
	Time- out	Elapse between the sequential "start"request cycle's.		25 µs

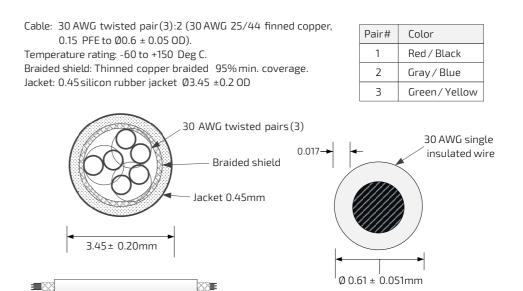


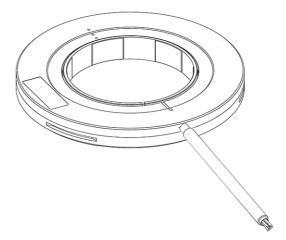


# Ordering Code

# **Cable Information**







Related documents DS-90 User Manual: Mechanical, Electrical and calibration setup.

# **Optional Accessories**

#### **Demonstration Kit**

DKIT-DS-90-SH-SO: (SSi Interface) DKIT-DS-90-IH-SO: (BiSS interface) Includes, mounted encoder on rotary jig, and RS-422 to USB converter.

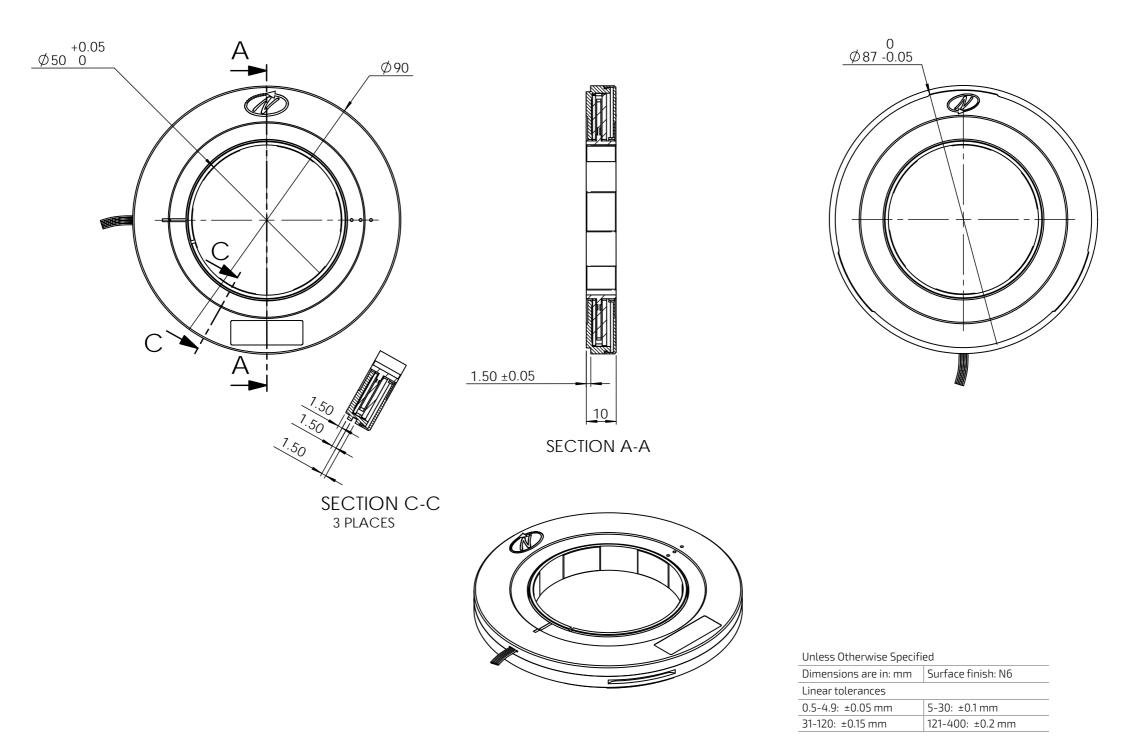
В

BIT





ICD DS-90-SH-S0 / DS-90-IH-S0



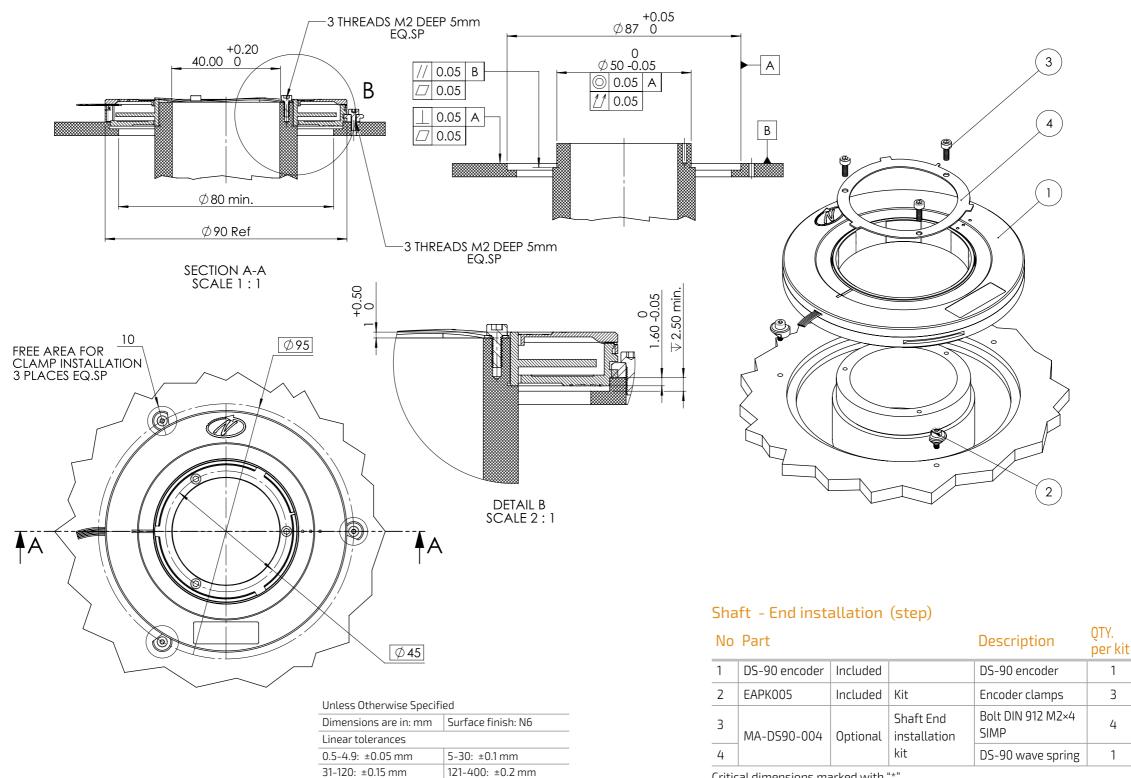
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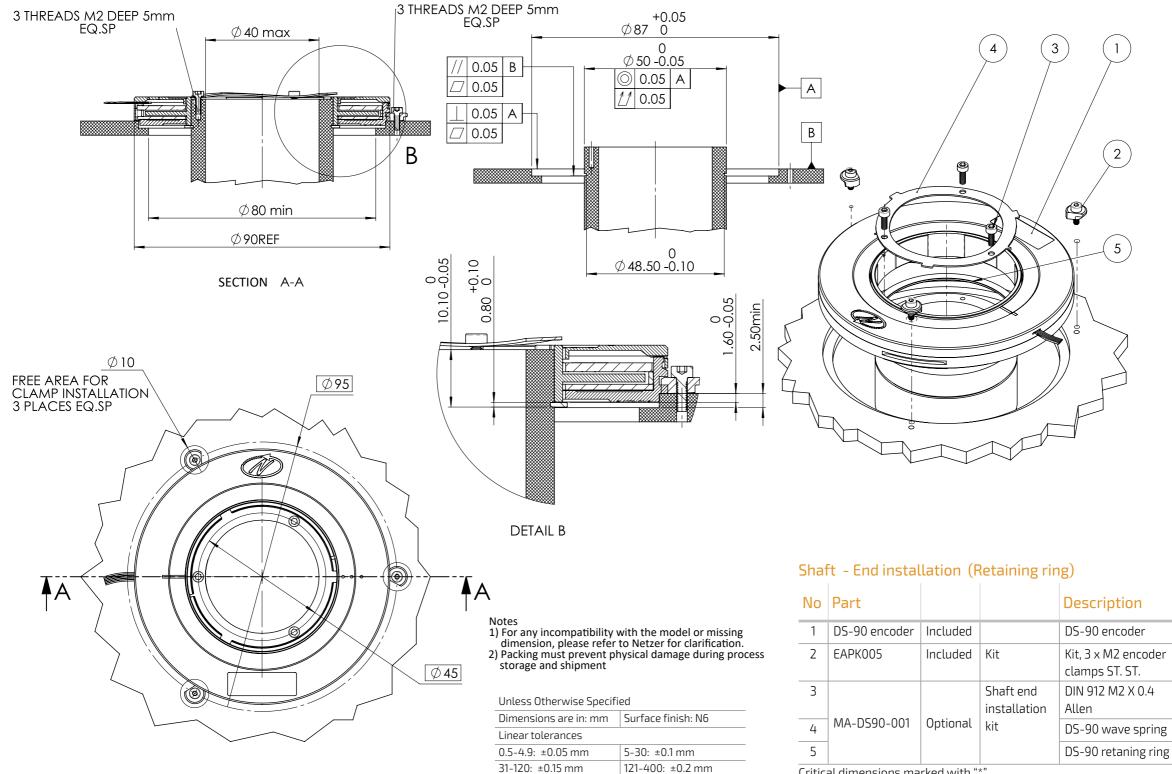
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Critical dimensions marked with "\*"







Critical dimensions marked with "\*"

DS-90-V02

QTY.

per kit

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